

Optimal Trade Execution with Instantaneous Price Impact and Stochastic Resilience

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Vienna, Nov. 18th, 2016

¹Based on joint work with Paulwin Graewe

- portfolio liquidation model with
 - instantaneous price impact
 - permanent price impact
 - stochastic resilience
 - only absolutely continuous trading strategies
- what's new?
 - value functions can be described by a coupled BSDE system
 - one component has a singular terminal condition
 - solved using asymptotic expansion at the terminal time

- models with instantaneous price impact
 - LQ cost function
 - absolutely continuous strategies
 - value functions described by one-dimensional PDEs, B(S)PDEs
- models with permanent price impact and resilience
 - LQ cost function
 - absolutely continuous and block trades
 - absolutely continuous trades: permanent impact
 - block trades: instantaneous and permanent impact
 - optimal strategy characterised in terms of BSDE (systems)

- only absolutely continuous strategies (value function)
- persistent price impact with only a.c. strategies:
 - trading rate adds drift to a benchmark price
 - impact of past trades on current prices decreases
- instantaneous impact with only a.c. strategies:
 - no instantaneous impact: trade infinitely fast
 - weak instantaneous impact: trade fast initially
 - large instantaneous impact: “no permanent impact”

- the control problem
- the BSDE system for the value function
- solving the BSDE system
- the verification argument

The control problem

The control problem

For any initial state $(t, x, y) \in [0, T) \times \mathbb{R} \times \mathbb{R}$ the value function is

$$V_t(x, y) = \operatorname{ess\,inf}_{\xi \in \mathcal{A}(t, x)} \mathbb{E} \left[\int_t^T \frac{1}{2} \eta \xi_s^2 + \xi_s Y_s + \frac{1}{2} \lambda_s X_s^2 ds \mid \mathcal{F}_t \right]$$

where

$$\begin{cases} dX_s = -\xi_s ds, & t \leq s \leq T; & X_t = x; \\ dY_s = \{-\rho_s Y_s + \gamma \xi_s\} ds, & t \leq s \leq T; & Y_t = y. \end{cases}$$

The process $\xi \in L^2_{\mathcal{F}}(t, T; \mathbb{R})$ is the *control* and

$$\eta, \gamma \in \mathbb{R}_+; \quad \rho, \lambda \in L^\infty_{\mathcal{F}}(0, T; \mathbb{R}_+).$$

Remark

$\rho \equiv 0$ ($y = 0$): *only temporary impact.*

The control problem

A control is called *admissible* if the terminal state constraint

$$X_T = 0$$

is satisfied a.s. and

$$\xi \in L^2_{\mathcal{F}}(t, T; \mathbb{R}).$$

The set of all admissible controls is denoted

$$\mathcal{A}(t, x).$$

Remark

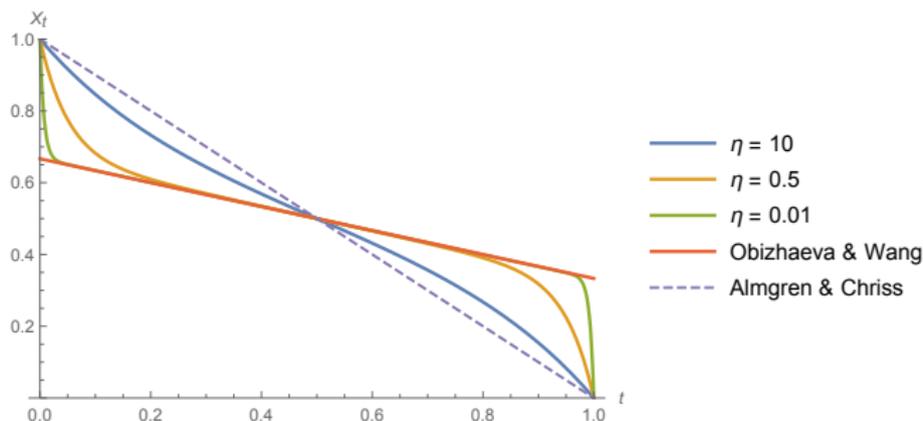
Since $\xi \in L^2_{\mathcal{F}}(t, T; \mathbb{R})$ boundedness of the coefficients guarantees

$$X, Y \in L^2_{\mathcal{F}}(\Omega; C([t, T]; \mathbb{R})).$$

The control problem

Recall that

$$V_t(x, y) = \operatorname{ess\,inf}_{\xi \in \mathcal{A}(t, x)} \mathbb{E} \left[\int_t^T \frac{1}{2} \eta \xi_s^2 + \xi_s Y_s + \frac{1}{2} \lambda_s X_s^2 ds \mid \mathcal{F}_t \right]$$



The HJB equation

The stochastic HJB equation to our problem is

$$-dV_t(x, y) = \inf_{\xi \in \mathbb{R}} \{ \dots \partial_x V_t(x, y) \dots \partial_y V_t(x, y) \dots \} dt - Z_t(x, y) dW_t.$$

Remark

The HJB equation is given by the cost function and the state dynamics; the terminal condition by the liquidation constraint.

The HJB equation

The LQ structure of the control problem suggest the ansatz

$$\begin{aligned}V_t(x, y) &= \frac{1}{2}A_t x^2 + B_t xy + \frac{1}{2}C_t y^2 \\Z_t(x, y) &= \frac{1}{2}Z_t^A x^2 + Z_t^B xy + \frac{1}{2}Z_t^C y^2\end{aligned}$$

for the solution $(V(x, y), Z(x, y))$ to the HJB equation, where

$$\begin{cases} -dA_t = \{ \lambda_t - \eta^{-1}(A_t - \gamma B_t)^2 \} dt - Z_t^A dW_t \\ -dB_t = \{ -\rho_t B_t + \eta^{-1}(\gamma C_t - B_t + 1)(A_t - \gamma B_t) \} dt - Z_t^B dW_t \\ -dC_t = \{ -2\rho_t C_t - \eta^{-1}(\gamma C_t - B_t + 1)^2 \} dt - Z_t^C dW_t. \end{cases}$$

What is the terminal condition of this BSDE system?

The terminal condition

- we expect the trading rate ξ to tend to infinity for any non-trivial initial position as $t \rightarrow T$.
- we expect the resulting trading cost to dominate any resilience effect.
- we expect that

$$V_t(x, y) \sim V_t^{\rho=0}(x, y) \quad \text{as } t \rightarrow T$$

where $V^{\rho=0}$ is the value function corresponding to $\rho \equiv 0$.

Lemma (The case $\rho \equiv 0$ (Graewe, H and Qiu (2015)))

$$V_t^{\rho=0}(x, y) = \frac{1}{2}(\tilde{A}_t + \gamma)x^2 + xy,$$

where

$$\begin{cases} -d\tilde{A}_t = \lambda_t - \eta^{-1}\tilde{A}_t^2 dt - Z_t dW_t \\ \tilde{A}_t \rightarrow \infty \text{ in } L^\infty \text{ as } t \rightarrow T \end{cases}.$$

Remark

From this lemma we see why $\rho \equiv 0$ corresponds to a model with only temporary impact.

The terminal condition

Since

$$V_t^{\rho=0}(x, y) = \frac{1}{2}(\tilde{A}_t + \gamma)x^2 + xy,$$

and in view of the ansatz

$$V_t(x, y) = \frac{1}{2}A_t x^2 + B_t xy + \frac{1}{2}C_t y^2$$

we expect the coefficients of the linear-quadratic ansatz to satisfy

$$(A_t, B_t, C_t) \longrightarrow (\infty, 1, 0) \quad \text{in } L^\infty \text{ as } t \rightarrow T.$$

Remark

Our approach uses the precise rate of “ $A_t \rightarrow \infty$ in L^∞ ”.

Theorem (Existence and uniqueness of solutions)

- *The above BSDE system imposed with the above singular terminal condition admits at least one solution*

$$\begin{aligned} & ((A, B, C), (Z^A, Z^B, Z^C)) \\ & \in L^\infty_{\mathcal{F}}(\Omega; C([0, T^-]; \mathbb{R}^3)) \times L^2_{\mathcal{F}}(0, T^-; \mathbb{R}^{3 \times m}). \end{aligned}$$

- *Suppose a solution exists, then the value function is of the linear quadratic form and the optimal strategy is*

$$\xi_t^*(x, y) = \eta^{-1}(A_t - \gamma B_t)x - \eta^{-1}(\gamma C_t - B_t + 1)y.$$

In particular, the BSDE systems admits at most one solution.

Remark

Recall that

$$\xi_t^*(x, y) = \eta^{-1}(A_t - \gamma B_t)x - \eta^{-1}(\gamma C_t - B_t + 1)y.$$

We show that

$$A_t - \gamma B_t > 0; \quad \gamma C_t - B_t + 1 \geq 0$$

but we have no result on the sign of ξ^ along (X^*, Y^*) . We can not rule out 'price triggered round trips'.*

Solving the BSDE system

The BSDE system

We need to solve a fully coupled BSDE system

- with singular terminal condition
- to which multi-dimensional comparison results don't apply

The idea is to find an equivalent BSDE system

- with regular terminal condition
- but singular driver

that can be solved in a suitable space: as $t \rightarrow T$:

$$A_t = \frac{\eta}{T-t} + \frac{H_t}{(T-t)^2}, \quad B_t = 1 + \frac{G_t}{T-t}, \quad C_t = P_t$$

where

$$H_t, B_t, C_t = O((T-t)^2).$$

Recall that

$$\begin{cases} -dA_t = \{ \lambda_t - \eta^{-1}(A_t - \gamma B_t)^2 \} dt - Z_t^A dW_t \\ -dB_t = \{ -\rho_t B_t + \eta^{-1}(\gamma C_t - B_t + 1)(A_t - \gamma B_t) \} dt - Z_t^B dW_t \\ -dC_t = \{ -2\rho_t C_t - \eta^{-1}(\gamma C_t - B_t + 1)^2 \} dt - Z_t^C dW_t. \end{cases}$$

- $B_T = 1 \Rightarrow A$ behaves as in the one-dimensional case
- rate of convergence of B is slower than that of C
- $A_t \sim \frac{1}{T-t} \Rightarrow B_t - 1 = O(T - t)$

Let

$$((A, B, C), (Z^A, Z^B, Z^C))$$

denote any solution to our BSDE system that satisfies

$$(A_t, B_t, C_t) \longrightarrow (\infty, 1, 0) \quad \text{in } L^\infty \text{ as } t \rightarrow T.$$

It will be necessary to also consider the processes

$$D := \eta^{-1}(A - \gamma B) \quad \text{and} \quad E := \eta^{-1}(\gamma C - B + 1)$$

that appear in the characterization of the candidate strategy.

Remark

We need the full picture: value function and strategy. The BSDEs for D, E and the system for (B, D) allow for comparison.

Using multi-dimensional comparison we can show that a.s.

$$A, D \geq 0, \quad B, -\gamma C, \eta E \in [0, 1]$$

Since

$$\xi_t^*(x, y) = D_t x - E_t y$$

this does not guarantee that $\xi^* \geq 0$.

- using a comparison principle for quasi-monotone BSDE systems we obtain a priori estimates for B, D and E
- from these we conclude that the following asymptotic behaviors hold in L^∞ as $t \rightarrow T$:

$$(T - t)A_t = \eta + O(T - t),$$

$$B_t = 1 + O(T - t),$$

$$C_t = O((T - t)^3).$$

The asymptotic behavior suggests the following ansatz:

$$A_t = \frac{\eta}{T-t} + \frac{H_t}{(T-t)^2}, \quad H_t = O((T-t)^2)$$

$$B_t = 1 + \frac{G_t}{T-t}, \quad G_t = O((T-t)^2)$$

$$C_t = P_t, \quad P_t = O((T-t)^2)$$

where H , G and P are of the form

$$-dY_t = \left\{ \dots - \left(\frac{Y_t}{T-t} + \text{coupling} \right)^p \right\} dt + Z_t dW_t.$$

We have a BSDE system with singular driver,

$$-dY_t = f(\omega, t, Y_t)dt - Z_t dW_t$$

We need to look for a solution in the right space, namely

$$\mathcal{H} = \{Y \in L^\infty_{\mathcal{F}}(\Omega; C([T - \delta, T]; \mathbb{R}^3)) : \|Y\|_{\mathcal{H}} < +\infty\}$$

endowed with the norm

$$\|Y\|_{\mathcal{H}} = \|(T - \cdot)^{-2} Y\|_{L^\infty_{\mathcal{F}}(\Omega; C([T - \delta, T]; \mathbb{R}^3))}.$$

This space is complete and the driver f is locally Lipschitz:

$$\|f(\cdot, Y) - f(\cdot, X)\|_{\mathcal{H}} \leq L \|Y - X\|_{\mathcal{H}} \quad \forall Y, X \in \overline{B}_{\mathcal{H}}(R).$$

Lemma

- *There exists a short-time solution*

$$(Y, Z) \in \mathcal{H}^2 \times L^2_{\mathcal{F}}(T - \delta, T; \mathbb{R}^{3 \times m})$$

to the above BSDE with singular driver.

- *In particular, there exists a small time solution to the BSDE system for (A, B, C) with singular terminal value.*
- *The small time solution for (A, B, C) can be extended to a global solution on $[0, T)$.*

Remark

The extension uses that f is independent of Z , analogously to PDEs, when the inhomogeneity is independent of the gradient.

Verification

- we can apply Itô on $[0, s]$ for all $s < T$ to get:

$$V_t(x, y) \leq \mathbb{E}_t[V_s(X_s, Y_s)] \\ + \mathbb{E}_t \left[\int_t^s \left\{ \frac{1}{2} \eta \xi_r^2 + \xi_r Y_r + \frac{1}{2} \lambda_r X_r^2 \right\} dr \right].$$

with equality for the candidate strategy ξ^*

Lemma

- *the candidate is admissible and*

$$\xi^*, Y^* \in L^\infty_{\mathcal{F}}(\Omega; C([t, T]; \mathbb{R})).$$

- *for every $\xi \in \mathcal{A}(t, x)$ it holds that*

$$E_t[A_s X_s^2 + B_s X_s Y_s + C_s Y_s^2] \xrightarrow{s \rightarrow T} 0.$$

By the Itô-Kunita formula we have (after stopping):

$$V_t(x, y) \leq \mathbb{E}_t[V_S(X_S, Y_S)] + \mathbb{E}_t \left[\int_t^S \left\{ \frac{1}{2} \eta \xi_r^2 + \xi_r Y_r + \frac{1}{2} \lambda_r X_r^2 \right\} dr \right].$$

Since $X, Y \in L^2_{\mathcal{F}}(\Omega; C([t, T]; \mathbb{R}))$, and $\xi \in L^2_{\mathcal{F}}(t, T; \mathbb{R})$, we get

$$V_t(x, y) \leq \mathbb{E}_t \left[\int_t^T \left\{ \frac{1}{2} \eta \xi_r^2 + \xi_r Y_r + \frac{1}{2} \lambda_r X_r^2 \right\} dr \right].$$

- liquidation model with instantaneous and permanent impact
- main results:
 - value function is characterised by a BSDE system
 - BSDE system satisfies a singular terminal condition
 - existence via an asymptotic expansion at the terminal time
- main limiting factors:
 - a priori estimates
 - comparison result
- some open problems:
 - sign of the optimal trading strategy
 - introduce dark pools
 - random order book height (liquidity)
 - convergence as $\eta \rightarrow 0$
 - ...

Many Thanks!