Distributional Time Series

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References

Main Contents: Theory

- Park and Qian (2012), Functional Regression of Continuous State Distributions, Journal of Econometrics.
- ▶ Chang, Kim and Park (2015), Nonstationarity in Time Series of State Densities, Forthcoming in *Journal of Econometrics*.
- ► Chang, Kim and Park (2015), Common Trends in Time Series of Cross Sectional Distributions.
- ► Chang, Kim and Park (2015), Functional Autoregressions with Unit Roots.

References

Main Contents: Applications

- Chang, Kim, Miller, Park and Park (2015), Time Series Analysis of Global Temperature Distributions: Identifying and Estimating Persistent Features in Temperature Anomalies.
- ▶ Baek, Chang, Kim and Park (2015), An Empirical Analysis of Income and Consumption Distributions in UK.
- ► Chang, Hong, Kim and Park (2015), An Empirical Analysis of World Income Distributions.

Background Material

Bosq (2000), Linear Processes in Function Spaces.

Outline

- I. Basic Framework
- **II. Distributional Unit Roots**
- **III. Distributional Cointegration**
- IV. Future Work

I. Basic Framework

Objective

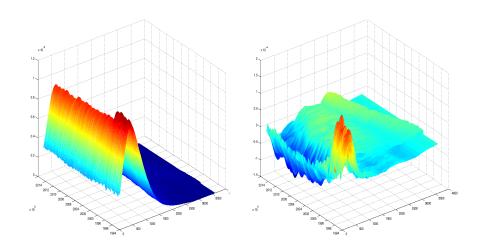
Develop a new framework and methodology to analyze the time series of cross-sectional distributions such as

- individual earnings
- global temperatures
- household income
- household expenditures

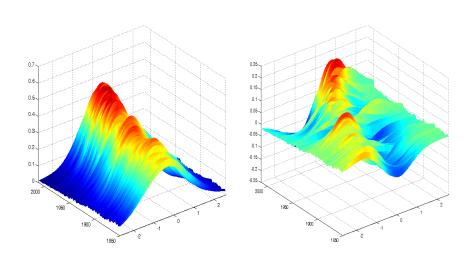
or the time series of intra-period distributions such as

stock returns

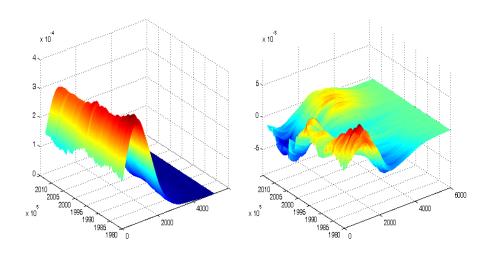
Distributions of Individual Earnings



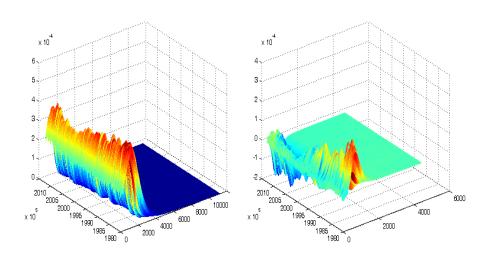
Global Temperature Distributions



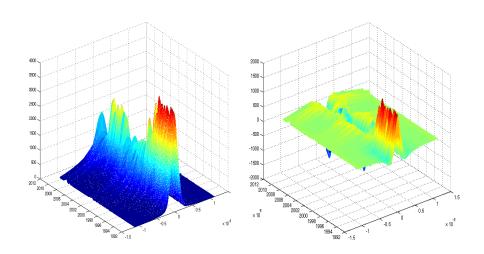
Distributions of Household Income



Distributions of Household Expenditures



Intra-month Distributions of S&P 500 Returns



Technical Background

Hilbert-Valued Random Variables

Let

$$w: \Omega \to H$$

where H is a Hilbert space.

Hilbert-valued random variables include

- Real random variables: $H = \mathbb{R}$
- Vector-valued random variables: $H = \mathbb{R}^N$
- Function-valued random variables: $H = L^2(\mathbb{R})$

Expectation and Variance Operators

Expectation $\mathbb{E} w$ of $w \in H$ is defined as a vector in H satisfying

$$\langle v, \mathbb{E}w \rangle = \mathbb{E}\langle v, w \rangle$$

for all $v \in H$. $\mathbb{E}w$ exists iff $\mathbb{E}||w|| < \infty$.

Variance Σ of w is given by an operator for which

$$\mathbb{E}\langle v_i, w - \mathbb{E}w \rangle \langle v_j, w - \mathbb{E}w \rangle = \langle v_i, \Sigma v_j \rangle$$

for all $v_i, v_j \in H$.

- ▶ For $w \in H$ with $\mathbb{E}w = 0$, $\mathbb{E}\langle v_i, w \rangle \langle v_j, w \rangle = \langle v_i, \mathbb{E}(w \otimes w)v_j \rangle$, and Σ is given simply by the expected tensor product $\mathbb{E}(w \otimes w)$.
- ▶ For a finite dimensional w, $\mathbb{E}(w \otimes w)$ reduces to $\mathbb{E}ww'$.

Unit Root in Function Space

In a simple functional AR(1) model

$$w_t = Aw_{t-1} + u_t,$$

where (u_t) is now an iid sequence of random functionals. For each realization of (u_t) , we have a random function, and A is a linear operator transforming a function into another function.

Consequently, for each realization of (u_t) , we have

$$w_t = u_t + Au_{t-1} + A^2u_{t-2} + \cdots$$

Mean Reversion and Persistency in Function Space

The mean reversion property of (w_t) is determined by the norm ||A||.

- (w_t) is stationary if ||A|| < 1, i.e., ||Av|| < ||v|| for all v. Mean reversion in all directions. Deviates from mean only temporarily, and randomly fluctuates around the mean in all directions.
- ▶ (w_t) has a unit root in the direction of v if ||Av|| = ||v||. Persistent, and non mean reverting due to the presence a stochastic trend with no mean reversion in the direction of v.
- (w_t) is explosive in the direction of v if ||Av|| > ||v||. No mean reversion in the direction of v.

We provide a mathematical framework to more explicitly identify and analyze the unit root and cointegration directions in the function space of state densities.

II. Distributional Unit Roots

Model for Functional Data

- For each time $t=1,2,\ldots$, suppose there is a distribution represented by a probability density f_t , whose value at ordinate $s\in\mathbb{R}$ is denoted by $f_t(s)$.
- Denote by

$$w_t = f_t - \mathbb{E}f_t$$

a demeaned density function and treat w_t as functional data taking values in Hilbert space H.

▶ We define H to be the set of functions on a compact subset K of \mathbb{R} that have vanishing integrals and are square integrable, i.e.,

$$H = \left\{ w \left| \int_K w(s)ds = 0, \int_K w^2(s)ds < \infty \right. \right\}$$

with inner product $\langle v, w \rangle = \int v(s)w(s)ds$ for $v, w \in H$.

Coordinate Process

lacktriangle We assume that there exists an orthonormal basis (v_i) of H such that

$$w_t = \sum_{i=1}^{\infty} \langle v_i, w_t \rangle v_i$$

► And the *i*-th coordinate process

$$\langle v_i, w_t \rangle$$

has a unit root for $i=1,\ldots,n$, while it is stationary for all $i\geq n+1$.

▶ By convention, we set n = 0 if all the coordinate processes are stationary.

Unit Root and Stationarity Subspaces

▶ Using the symbol \(\forall \) to denote span, we let

$$H_N = \bigvee_{i=1}^n v_i$$
 and $H_S = \bigvee_{i=n+1}^\infty v_i$

so that $H=H_N\oplus H_S$. In what follows, H_N and H_S will respectively be referred to as the unit root and stationarity subspaces of H.

▶ We also let Π_N and Π_S be the projections on H_N and H_S , respectively. Moreover, we define

$$w_t^N = \Pi_N w_t$$
 and $w_t^S = \Pi_S w_t$

Note that $\Pi_N + \Pi_S = 1$ (the identity operator on H), so in particular we have

$$w_t = w_t^N + w_t^S$$

Unit Root and Stationary Processes

▶ When $u_t = \triangle w_t = \Phi(L)\varepsilon_t$, it follows that

$$w_t^N = \Pi_N w_t = \Pi_N \Phi(1) \sum_{i=1}^t \varepsilon_i - \Pi_N \bar{u}_t$$

and

$$w_t^S = \Pi_S w_t = -\Pi_S \bar{u}_t$$

Clearly, (w_t^N) is an integrated process, while (w_t^S) is stationary.

- ► The unit root dimension *n* is unknown in practical applications.
- ► We will explain how to
 - o Determine n statistically
 - o Estimate the subspaces H_S and H_N

Sample Variance Operator

lackbox Our test for unit roots in (w_t) is based on the sample variance operator

$$M^T = \sum_{t=1}^T w_t \otimes w_t,$$

whose quadratic form is given by

$$\langle v, M^T v \rangle = \sum_{t=1}^{T} \langle v, w_t \rangle^2$$

for $v \in H$.

Asymptotic behavior of the quadratic form of sample variance operator depends crucially on whether v is in H_N or in H_S .

Stationarity-Nonstationarity of Coordinate Processes

▶ For $v \in H_S$, the coordinate process $(\langle v, w_t \rangle)$ becomes stationary and we expect that

$$T^{-1} \sum_{t=1}^{T} \langle v, w_t \rangle^2 \to_p \mathbb{E} \langle v, w_t \rangle^2$$

as long as the expectation exists.

▶ On the other hand, if $v \in H_N$ and the coordinate process $(\langle v, w_t \rangle)$ is integrated, it follows under a very mild condition that

$$T^{-2} \sum_{t=1}^{T} \langle v, w_t \rangle^2 \to_d \int_0^1 V(r)^2 dr - \left(\int_0^1 V(r) dr \right)^2,$$

where V is a Brownian motion.

▶ Therefore, the quadratic form has different orders of magnitude, i.e., $O_p(T)$ and $O_p(T^2)$, depending upon whether the coordinate process $(\langle v, w_t \rangle)$ is stationary or integrated.

Nonstationarity and Stationarity Subspaces

- ▶ We let H_N be n-dimensional.
- ▶ Denote by v_1^T, v_2^T, \ldots the orthonormal eigenvectors of the sample variance operator M^T .
- It is shown that

$$v_i^T \to_p v_i$$

for $i=1,2,\ldots$, as $T\to\infty$.

Estimation of Nonstationarity Subspace

▶ Once we determine the number of unit roots n in (w_t) , we may estimate the nonstationarity subspace H_N by

$$H_N^T = \bigvee_{i=1}^n v_i^T,$$

i.e., the span of the n orthonormal eigenvectors of the sample variance operator M^T associated with n largest eigenvalues of M_T .

Recall

$$H_N = \bigvee_{i=1}^n v_i$$
 and $H_S = \bigvee_{i=n+1}^\infty v_i$

▶ We establish the consistency of H_N^T for H_N .

Functional Principal Component Analysis

If we define $\lambda_1^T \geq \lambda_2^T \geq \cdots$ to be the eigenvalues of M^T associated with the eigenvectors v_1^T, v_2^T, \ldots , then we have

$$\lambda_i^T = \langle v_i^T, M^T v_i^T \rangle = \sum_{t=1}^T \langle v_i^T, w_t \rangle^2$$

for i = 1, 2, ...

Therefore, it follows that

$$\lambda_i^T = \begin{cases} O_p(T^2) & \text{for } i = 1, \dots, n \\ O_p(T) & \text{for } i = n + 1, \dots \end{cases},$$

Onto Testing for Distributional Unit Roots

▶ To determine the number of unit roots in (w_t) , we consider the test of the null hypothesis

$$H_0$$
: dim $(H_N) = n$

against the alternative hypothesis

$$H_1: \dim(H_N) \le n-1$$

successively downward.

- ▶ More precisely, we start testing the null with $n = n_{\text{max}}$, where n_{max} is large enough so that dim $(H_N) \le n_{\text{max}}$.
- ▶ Continue with $n = n_{\text{max}} 1$ if the null is rejected in favor of the alternative. If, for any n, dim $(H_N) \le n$ and the null is not rejected, then we may conclude that dim $(H_N) = n$.
- ▶ Therefore, we may estimate the number of unit roots in (w_t) by the smallest value of n for which we fail to reject the null.

Intuitive but Infeasible Test

- We expect that the eigenvalue λ_n^T would have a discriminatory power for the test of null against the alternative, since it has different orders of stochastic magnitudes under the null and alternative hypotheses.
- ► However, it cannot be used directly as a test statistic, since its limit distribution is dependent upon nuisance parameters.
- Therefore, we need to modify it appropriately to get rid of its nuisance parameter dependency problem.

A Feasible Test for Unit Root Dimension

▶ To introduce our test, define (z_t^T) for t = 1, ..., T by

$$z_t^T = (\langle v_1^T, w_t \rangle, \dots, \langle v_n^T, w_t \rangle)'$$

- Also define the product sample moment $M_n^T = \sum_{t=1}^T z_t^T z_t^{T\prime}$ (sample variance in the unit root subspace), and the long-run variance estimator $\Omega_n^T = \sum_{|k| \leq \ell} \varpi_\ell(k) \Gamma_T(k)$ of (z_t^T) , where ϖ_ℓ is the weight function with bandwidth parameter ℓ and Γ_T is the sample autocovariance function defined as $\Gamma_T(k) = T^{-1} \sum_t \Delta z_t^T \Delta z_{t-k}^{T\prime}$.
- Our test statistic is defined as

$$\tau_n^T = T^{-2} \lambda_{\min} \left(M_n^T, \Omega_n^T \right),$$

where $\lambda_{\min}\left(M_n^T,\Omega_n^T\right)$ is the smallest generalized eigenvalue of M_n^T with respect to Ω_n^T .

Asymptotics for Distributional Unit Root Test

Under very general conditions, we show that

$$\tau_n^T \to_d \lambda_{\min} \left(\int_0^1 W_n(r) W_n(r)' dr - \int_0^1 W_n(r) dr \int_0^1 W_n(r)' dr \right)$$

under the null, as $T \to \infty$, where W_n is n-dimensional standard vector Brownian motion and $\lambda_{\min}(\cdot)$ denotes the smallest eigenvalue of its matrix argument.

- ▶ On the other hand, we have $\tau_n^T \to_p 0$ under the alternative as $T \to \infty$.
- ▶ Therefore, we reject the null in favor of the alternative if the test statistic τ_n^T takes small values.

Critical Values for Distributional Unit Root Test τ_n^T

- ▶ Critical values for the tests are obtained based on τ_n^T for $n=1,\ldots,5$, by simulations.
- ► For simulations, BM is approximated by standardized partial sum of mean zero i.i.d. normal random variates with sample size 10,000, and actual critical values are computed using 100,000 iterations.

| n | 1 | 2 | 3 | 4 | 5 |
|-----|--------|--------|--------|--------|--------|
| 1% | 0.0274 | 0.0175 | 0.0118 | 0.0103 | 0.0085 |
| 5% | 0.0385 | 0.0223 | 0.0154 | 0.0127 | 0.0101 |
| 10% | 0.0478 | 0.0267 | 0.0175 | 0.0139 | 0.0111 |

Degree of Persistency in Moments

- ► We may now find how much nonstationarity proportion exists in each cross-sectional moment.
- ▶ In what follows, we redefine ι_{κ} as $\iota_{\kappa} \frac{1}{|K|} \int_{K} \iota_{\kappa}(s) ds$, so that we may regard it as an element in H.
- ▶ We may decompose ι_{κ} as $\iota_{\kappa} = \prod_{N} \iota_{\kappa} + \prod_{S} \iota_{\kappa}$, from which it follows that

$$\|\iota_{\kappa}\|^{2} = \|\Pi_{N}\iota_{\kappa}\|^{2} + \|\Pi_{S}\iota_{\kappa}\|^{2} = \sum_{i=1}^{n} \langle\iota_{\kappa}, v_{i}\rangle^{2} + \sum_{i=n+1}^{\infty} \langle\iota_{\kappa}, v_{i}\rangle^{2},$$

where (v_i) , $i=1,2,\ldots$, is an orthonormal basis of H such that $(v_i)_{1\leq i\leq n}$ and $(v_i)_{i\geq n+1}$ span H_N and H_S , respectively.

Nonstationarity Proportion in Moments

▶ To measure the proportion of ι_{κ} lying in H_N , we define

$$\pi_{\kappa} = \frac{\|\Pi_{N} \iota_{\kappa}\|}{\|\iota_{\kappa}\|} = \sqrt{\frac{\sum_{i=1}^{n} \langle \iota_{\kappa}, v_{i} \rangle^{2}}{\sum_{i=1}^{\infty} \langle \iota_{\kappa}, v_{i} \rangle^{2}}}.$$

- $m \pi_\kappa=1$ and $\pi_\kappa=0$, respectively, if ι_κ is entirely in H_N and H_S .
- ▶ Therefore, we may use π_{κ} to represent the proportion of nonstationary component in the κ -th cross-sectional moment of (w_t) .
- ▶ The κ -th cross-sectional moment of (w_t) has more dominant unit root component as π_{κ} tends to unity, whereas it becomes more stationary as π_{κ} approaches to zero.

Sample Nonstationarity Proportion

- The nonstationarity proportion π_{κ} of the κ -th cross-sectional moment is not directly applicable, since H_N and H_S are unknown.
- ▶ However, we may use its sample version

$$\pi_{\kappa}^{T} = \sqrt{\frac{\sum_{i=1}^{n} \langle \iota_{\kappa}, v_{i}^{T} \rangle^{2}}{\sum_{i=1}^{T} \langle \iota_{\kappa}, v_{i}^{T} \rangle^{2}}}.$$

- ▶ The sample version π_{κ}^T of π_{κ} will be referred to as the sample nonstationarity proportion of the κ -th cross-sectional moment of (w_t) .
- ▶ We show that the sample version π_{κ}^{T} is a consistent estimator for the original π_{κ} .

Empirical Illustrations

Overview

- We demonstrate how to define and estimate the state densities, and test for unit roots in the time series of densities representing cross-sectional or intra-period distributions of economic variables.
- ightharpoonup State densities are estimated by standard kernel density estimation method on cross-sectional or intra-period observations, and their nonstationarities are analyzed using the test $\hat{\tau}_T^n$.
- ▶ Unit root dimension n of state densities is determined by applying $\hat{\tau}_T^n$ successively downward starting from $n = n_{\max}$.
- Unit root space H_N is then estimated and the unit root proportion (π_{κ}) is computed for the first several moments. π_{κ} provides the proportion of nonstationary fluctuation in the κ -th moment of the state distribution.

Representation of Functions as Numerical Vectors

- ► For the representation of infinite dimensional functions in Hilbert space as finite dimensional numerical vectors, we use a Daubechies wavelet basis.
- Wavelets are two dimensional arrays in location and resolutions, and hence they provide more flexibilities in fitting the state densities in our applications, some of which have severe asymmetry and time-varying support. The wavelet basis in general yields a much better fit than the trigonometric basis.
- ► The Daubechies wavelet is implemented with 1037 basis functions.

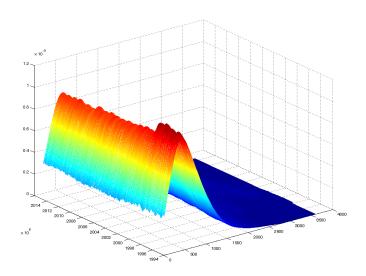
Cross-Sectional Distributions

of Individual Earnings

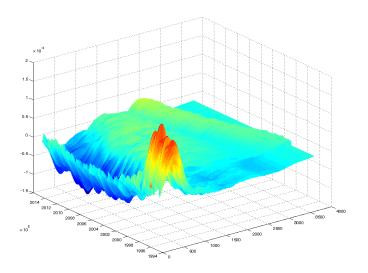
Distributions of Individual Earnings

- The cross-sectional observations of individual weekly earnings are obtained at monthly frequency from Current Population Survey (CPS) data set. The individual weekly earnings are deflated by consumer price index with base year 2005.
- ► The data set provides 247 time series observations spanning from January 1994 to July 2014, and the number of cross-sectional observations for each month ranges from 12,180 (April 1996) to 15,826 (October 2001).
- ▶ For confidentiality reasons, individual earnings are topcoded above a certain level. Top code value was revised in 1998 up to \$2,885 from \$1,923. We drop all topcoded individual earnings as well as zero earnings as in Liu (2011) and Shin and Solon (2011).

Densities of Weekly Individual Earnings



Demeaned Densities of Weekly Individual Earnings



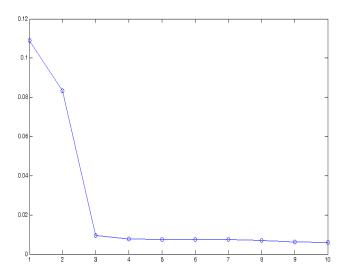
Unit Root Dimension - Individual Earnings

To determine the unit root dimension n in the time series of cross-sectional distributions of individual earnings, we use the statistic $\hat{\tau}_n^T$ to test for the null hypothesis $\mathsf{H}_0: \dim(H_N) = n$ against the alternative $\mathsf{H}_1: \dim(H_N) \leq n-1$ with $n=1,\ldots,5$.

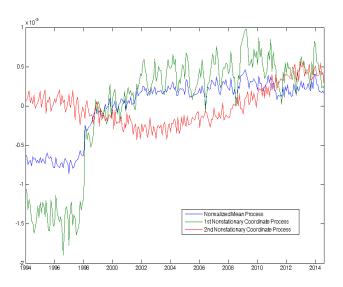
| \overline{M} | 1 | 2 | 3 | 4 | 5 |
|-----------------|--------|--------|--------|--------|--------|
| $\hat{	au}_n^T$ | 0.1090 | 0.0834 | 0.0094 | 0.0078 | 0.0075 |

- ▶ Our test, strongly and unambiguously, rejects H_0 against H_1 successively for n=5,4,3. Clearly, however, the test cannot reject H_0 in favor of H_1 for n=2.
- ▶ We conclude that there exists two-dimensional unit root, and set $\hat{n}_T = 2$.

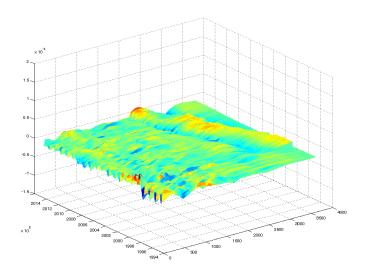
Scree Plot of Eigenvalues - Individual Earnings

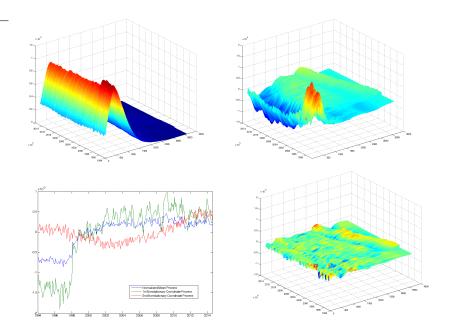


Integrated Coordinate Processes - Individual Earnings



Stationary Distributions - Individual Earnings





UR Proportions in Moments - Individual Earnings

We compute the estimates $\hat{\pi}_{\kappa}^{T}$ of the unit root proportions π_{κ} with $\hat{n}_{T}=2$ for the first four moments.

| $\hat{\pi}_1^T$ | $\hat{\pi}_2^T$ | $\hat{\pi}_3^T$ | $\hat{\pi}_4^T$ |
|-----------------|-----------------|-----------------|-----------------|
| 0.5280 | 0.3388 | 0.2377 | 0.1822 |

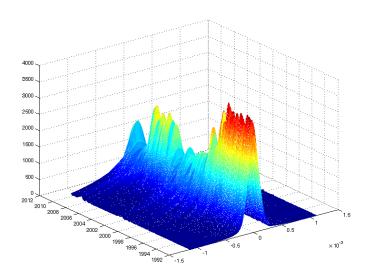
- ▶ The unit root proportions for the first four moments are all nonnegligibly large. In particular, the unit root proportions for the first two moments are quite substantial.
- ► The presence of a substantial unit root proportion in the second moment explains the recent empirical findings on changes in volatilities of individual earnings. Dynan et al (2008) and others.
- Nonstationarity in time series of individual earnings distributions would certainly make their volatilities more persistent.

Intra-Month Distributions of Stock Returns

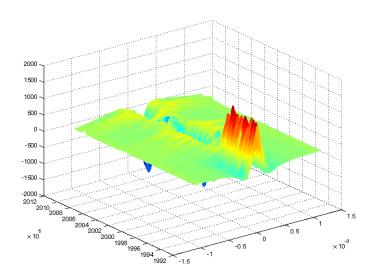
Intra-Month S&P 500 Return Distributions

- ▶ For each month during January 1992 to June 2010, we use S&P 500 index returns at one-minute frequency to estimate 222 densities for the intra-month distributions. The one-minute returns of S&P 500 index are obtained from Tick Data Inc. The number of intra-month observations varies from 7211 to 9177, except for September 2001, for which we only have 5982 observations.
- ► The intra-month observations are truncated at 0.50% and 99.5% percentiles before we estimate the state densities.
- To avoid micro-structure noise, we also use the five-minute observations to estimate the intra-month observations. Our empirical results are, however, virtually unchanged.

Intra-month S&P 500 Returns



Demeaned Intra-Month S&P 500 Returns



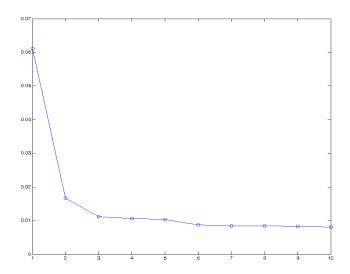
Unit Root Dimension - S&P 500 Returns

To test for existence of nonstationarity in time series of intra-month S&P 500 return distributions, we use $\hat{\tau}_n^T$ to test $\mathsf{H}_0: \dim(H_N) = n$ against $\mathsf{H}_1: \dim(H_N) \leq n-1$ with $n=1,\ldots,5$.

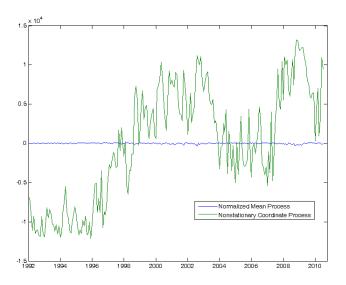
| \overline{M} | 1 | 2 | 3 | 4 | 5 |
|-----------------|--------|--------|--------|--------|---------|
| $\hat{	au}_n^T$ | 0.0612 | 0.0167 | 0.0112 | 0.0107 | 0.00104 |

- ▶ Our test successively rejects H_0 against H_1 for n = 5, 4, 3, 2.
- ▶ However, at 5% level, the test cannot reject H_0 in favor of H_1 for n=1. Our test result implies that there exists one-dimensional unit root, i.e., $\hat{n}_T = 1$.

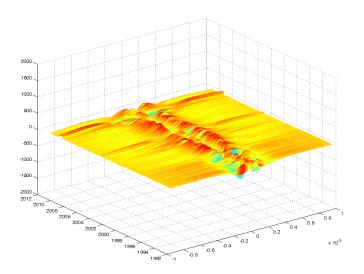
Scree Plot of Eigenvalues - S&P 500 Returns

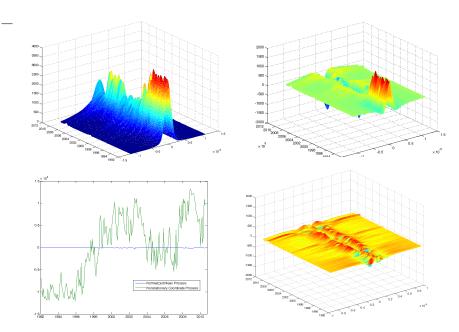


Integrated Coordinate Processes - S&P 500 Returns



Stationary Components - S&P 500 Returns





UR Proportions in Moments - S&P 500 Returns

Compute the estimates $\hat{\pi}_{\kappa}^{T}$ of the unit root proportions π_{κ} for the first four moments, with $\hat{n}_{T}=1$.

| $\hat{\pi}_1^T$ | $\hat{\pi}_2^T$ | $\hat{\pi}_3^T$ | $\hat{\pi}_4^T$ |
|-----------------|-----------------|-----------------|-----------------|
| 0.0047 | 0.2087 | 0.0039 | 0.0958 |

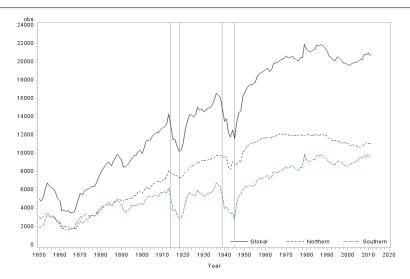
- ► The nonstationarity is more concentrated in the second and fourth moments, with the unit root proportion of the second moment being the largest.
- ► The unit root proportion of the first and third moments are almost negligible. This is well expected, since for many financial time series strong persistency is observed mainly in volatility and kurtosis.

Temperature Distributions

Data

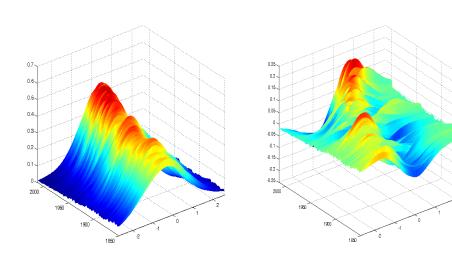
- Compiled by Climatic Research Unit at University of East Anglia and Hadley Centre of UK Met office.
- ► Global average of combined land and sea surface temperatures over widely dispersed locations, in a time series from 1850 to date (From 1,652 to 55,576 stations)
- Expressed as the deviation from the average of the period 1961-1990 and these deviations are called temperature anomalies.
- ▶ Temperature anomalies on a 5° by 5° grid-box basis (number of monthly grids : 36*72 = 2,592, number of annual grids: 2,592*12 = 31,104)

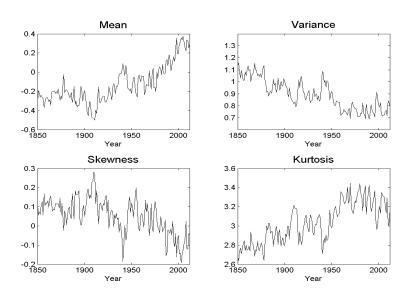
Number of Observations



Total number of 5° by 5° grid-boxes is 31,104(=36*72*12) for globe and 15,552(=18*72*12) for northern and southern hemisphere.

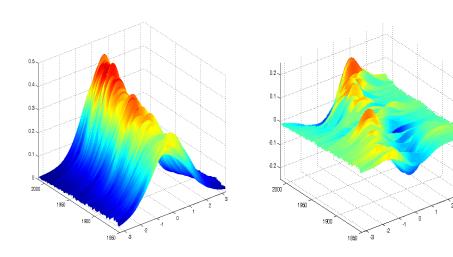
Temperature Densities - Globe

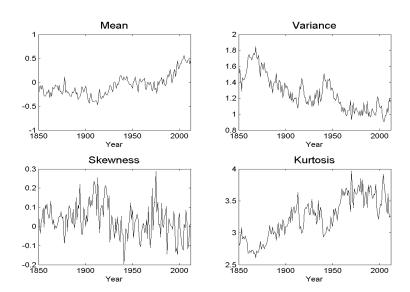




Mean, Variance, Skewness and Kurtosis for Globe

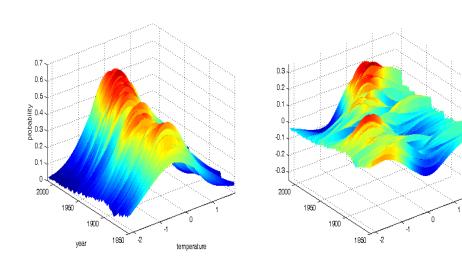
Temperature Densities - Northern Hemisphere

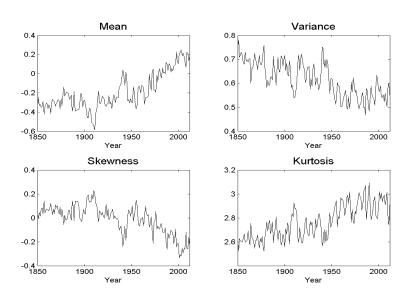




Mean, Variance, Skewness and Kurtosis for Northern Hemisphere

Temperature Densities - Southern Hemisphere





Mean, Variance, Skewness and Kurtosis for Southern Hemisphere

Critical Values of the Test Statistics $\hat{\tau}_n^T$

| $\hat{\tau}_{n,1}^T$ | n=1 | n=2 | n=3 | n=4 | n=5 |
|----------------------|--------|--------|--------|--------|--------|
| 1% | 0.0274 | 0.0175 | 0.0118 | 0.0103 | 0.0085 |
| 5% | 0.0385 | 0.0223 | 0.0154 | 0.0127 | 0.0101 |
| 10% | 0.0478 | 0.0267 | 0.0175 | 0.0139 | 0.0111 |
| | | | | | |
| $\hat{	au}_{n,2}^T$ | | | | | |
| 99% | 0.7487 | 1.0073 | 1.2295 | 1.4078 | 1.5952 |
| 95% | 0.4660 | 0.6787 | 0.8645 | 1.0336 | 1.1892 |
| 90% | 0.3494 | 0.5399 | 0.7066 | 0.8574 | 1.0092 |

Findings for Globe

| (a) | Values | of Statistics | for | Testing $n=m$ |
|-----|--------|---------------|-----|---------------|
|-----|--------|---------------|-----|---------------|

| (-) | | | | | | | | | |
|----------------------|--------|--------|--------|--------|--|--|--|--|--|
| | n=1 | n=2 | n=3 | n=4 | | | | | |
| $\hat{\tau}_{n,1}^T$ | 0.0633 | 0.0296 | 0.0116 | 0.0116 | | | | | |
| $\hat{\tau}_{n,2}^T$ | 0.0633 | 0.0723 | | | | | | | |

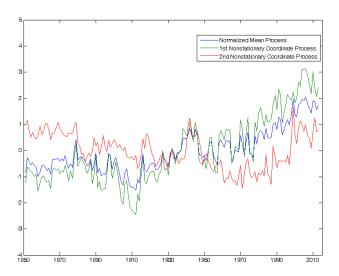
(b) Critical Values

| | n=1 | n=2 | n=3 | n=4 | |
|-----|--------|--------|--------|--------|--|
| 5% | 0.0385 | 0.0223 | 0.0154 | 0.0127 | |
| 95% | 0.4660 | 0.6787 | | | |

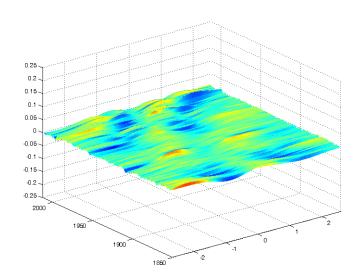
(c) Unit Root Proportions in First Seven Moments

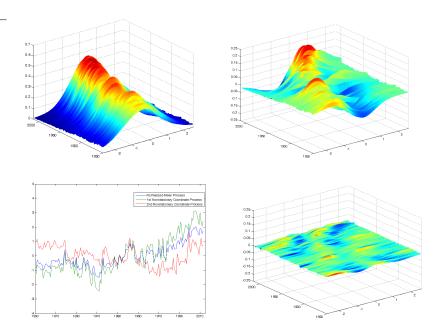
| $\hat{\pi}_1^T$ | $\hat{\pi}_2^T$ | $\hat{\pi}_3^T$ | $\hat{\pi}_4^T$ | $\hat{\pi}_5^T$ | $\hat{\pi}_6^T$ | $\hat{\pi}_7^T$ |
|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|
| 0.636 | 0.637 | 0.339 | 0.430 | 0.235 | 0.325 | 0.189 |

Nonstationary Coordinate Processes - Globe



Stationary Temperature Distributions - Globe





Findings for Northern Hemisphere

| (a) | Values | of Statistics | for | Testing | n=m |
|-----|--------|---------------|-----|---------|-----|
|-----|--------|---------------|-----|---------|-----|

| (=) | | | | | | | | |
|----------------------|--------|--------|--------|--------|--|--|--|--|
| | n=1 | n=2 | n=3 | n=4 | | | | |
| $\hat{\tau}_{n,1}^T$ | 0.0493 | 0.0423 | 0.0124 | 0.0119 | | | | |
| $\hat{	au}_{n,2}^T$ | 0.0493 | 0.0679 | | | | | | |
| | | | | | | | | |

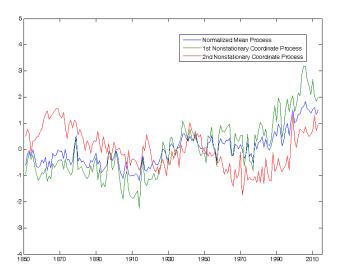
(b) Critical Values

| | n=1 | n=2 | n=3 | n=4 | |
|-----|--------|--------|--------|--------|--|
| 5% | 0.0385 | 0.0223 | 0.0154 | 0.0127 | |
| 95% | 0.4660 | 0.6787 | | | |

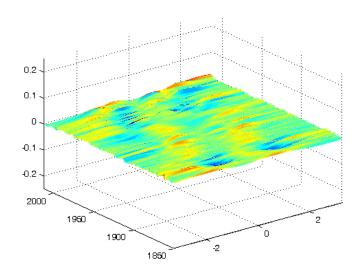
(c) Unit Root Proportions in First Seven Moments

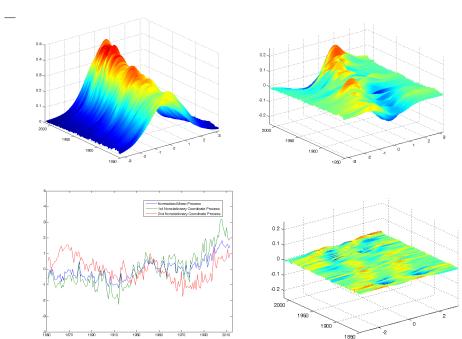
| $\hat{\pi}_1^T$ | $\hat{\pi}_2^T$ | $\hat{\pi}_3^T$ | $\hat{\pi}_4^T$ | $\hat{\pi}_5^T$ | $\hat{\pi}_6^T$ | $\hat{\pi}_7^T$ |
|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|-----------------|
| 0.578 | 0.567 | 0.283 | 0.361 | 0.187 | 0.266 | 0.147 |

Nonstationary Coordinate Processes - Northern



Stationary Temperature Distributions - Northern





Findings for Southern Hemisphere

| (a) | Values | of Statis | tics for | Testing | n=m |
|-----|---------------|-----------|----------|----------------|-----|
|-----|---------------|-----------|----------|----------------|-----|

| (-) | | | | | | | |
|----------------------|--------|--------|--------|--------|--|--|--|
| | n=1 | n=2 | n=3 | n=4 | | | |
| $\hat{\tau}_{n,1}^T$ | 0.0648 | 0.0205 | 0.0094 | 0.0086 | | | |
| $\hat{\tau}_{n,2}^T$ | 0.0648 | | | | | | |

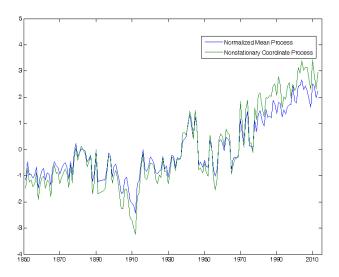
(b) Critical Values

| | n=1 | n=2 | n=3 | n=4 | |
|-----|--------|--------|--------|--------|--|
| 5% | 0.0385 | 0.0223 | 0.0154 | 0.0127 | |
| 95% | 0.4660 | | | | |

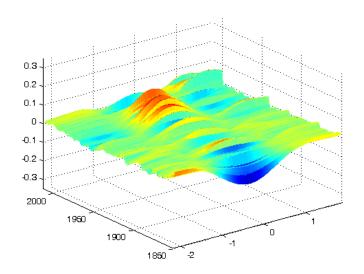
(c) Unit Root Proportions in First Seven Moments

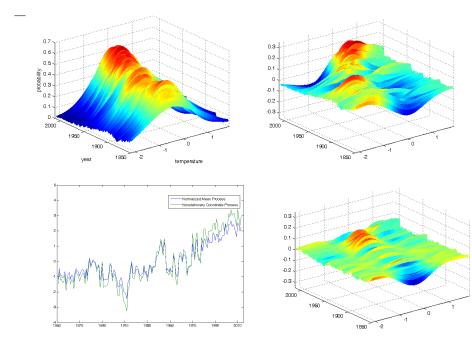
| \dot{T} | ^T | $^{\wedge}T$ | $^{\wedge}T$ | $^{\sim}T$ | ^ T | $^{\wedge}T$ |
|-----------|---------|--------------|--------------|------------|---------|---------------|
| π_1 | π_2 | π_3 | π_4 | π_5 | π_6 | π_7^{\pm} |
| 0.744 | 0.363 | 0.473 | 0.289 | 0.343 | 0.244 | 0.273 |

Nonstationary Coordinate Processess - Southern



Stationary Temperature Distributions - Southern





III. Distributional Cointegration

Common Trends in Distributional Time Series

- Introduce a notion of distributional cointegration between two time series of densities representing cross-sectional distributions of some economic variables
- Explain how to estimate and test for such cointegrating relationships.

A New Framework

- ► To analyze time series of densities representing cross-sectional distributions allowing for unit root type of nonstationarity
- ► To analyze possible cointegration among cross-sectional distributions
- ► To learn and interpret both longrun and shortrun relationships between two time series of cross-sectional distributions

Model and Methodology

Distributional Time Series

- Let (f_t) and (g_t) be two time series of densities representing cross-sectional distributions of some economic variables, which we call distributional time series for short.
- ▶ We regard the densities (f_t) and (g_t) as random elements taking values on the Hilbert space H of square integrable functions on \mathbb{R} .
- For the main application in the paper, we designate (f_t) and (g_t) respectively to be the monthly time series of densities for income and consumption distributions. They are of course not directly observable and should be estimated using cross-sectional observations on household income and consumption.
- However, to present our framework and methodology more effectively, we tentatively assume that they are observable.

Coordinate Processes

For the time series of densities (f_t) and (g_t) , we define

$$(\langle v, f_t \rangle)$$
 and $(\langle w, g_t \rangle)$

to be the coordinate processes of (f_t) and (g_t) respectively in the directions of v and w for any $v, w \in H$.

Cross-sectional Moments

▶ The coordinate processes of (f_t) and (g_t) in the direction of ι_{κ} , where

$$\iota_{\kappa}(s) = s^{\kappa},$$

are particularly important, since we have

$$\langle \iota_{\kappa}, f_{t} \rangle = \int s^{\kappa} f_{t}(s) ds$$
 and $\langle \iota_{\kappa}, g_{t} \rangle = \int s^{\kappa} g_{t}(s) ds$,

which represent the κ -th moments of the distributions represented by f_t and g_t for each $t=1,\ldots,T$.

▶ They will be referred subsequently to as the κ -th cross-sectional moments of (f_t) and (g_t) respectively.

Distributional Regression

We consider the distributional regression

$$g_t = \mu + Af_t + e_t$$

for $t=1,\ldots,T$, where regressand and regressor are time series of densities for cross-sectional distributions, μ and A are function and operator parameters, and (e_t) is a function-valued error process.

- ▶ Operator A generalizes regression coefficient in finite-dimensional regression, and may be called the regression operator.
- ▶ We allow for nonstationarity in both (f_t) and (g_t) . In particular, we let some of their coordinate processes $(\langle v, f_t \rangle)$ and $(\langle w, g_t \rangle)$ have unit roots and cointegration, which will be referred to as the distributional unit roots and cointegration.
- We assume that (e_t) is stationary and mean zero, i.e., $\mathbb{E}e_t=0$ for all $t=1,\ldots,T$, and impose some exogeneity condition for (f_t) .

Coordinate Regression

▶ Coordinate regression of (g_t) in any direction $w \in H$ can be readily obtained from our distributional regression as

$$\langle w, g_t \rangle = \langle w, \mu \rangle + \langle w, Af_t \rangle + \langle w, e_t \rangle$$
$$= \langle w, \mu \rangle + \langle A^*w, f_t \rangle + \langle w, e_t \rangle$$

for any $w \in H$, where A^* is the adjoint operator of A and $t = 1, \ldots, T$.

- ▶ Represents a relationship between particular coordinate processes of (g_t) and (f_t) .
- ▶ May be interpreted as the usual bivariate regression of the coordinate process $(\langle w, g_t \rangle)$ of (g_t) on the coordinate process $(\langle v, f_t \rangle)$ of (f_t) with $v = A^*w$ for any $w \in H$.
- ▶ Reveals the effect of the distribution represented by (f_t) on the coordinate process $(\langle w, g_t \rangle)$ of distribution (g_t) for $w \in H$.

More on Coordinate Regression

▶ The coordinate regression of (g_t) in any direction $w \in H$ is given as

$$\langle w, g_t \rangle = \langle w, \mu \rangle + \langle A^* w, f_t \rangle + \langle w, e_t \rangle$$

- ▶ The effect of the distribution represented by (f_t) on the coordinate process $(\langle w, g_t \rangle)$ is summarized by $v = A^*w$, which we call the response function of (f_t) to the coordinate process $(\langle w, g_t \rangle)$.
- If we set $w=\iota_{\kappa}$, the coordinate regression reveals how the κ -th cross- moment of (g_t) is affected by the distribution represented by (f_t) , and the response function $v=A^*w=A^*\iota_{\kappa}$ measures the effect of (f_t) on the κ -th cross-sectional moments of (g_t) .
- ▶ We analyze the coordinate regression separately for stationary and nonstationary components of (f_t) and (g_t) .

Regression in a Demeaned Form

We may consider the dist regression in a demeaned form as

$$y_t = Ax_t + \varepsilon_t,$$

where

$$x_t = f_t - \frac{1}{T} \sum_{t=1}^{T} f_t, \qquad y_t = g_t - \frac{1}{T} \sum_{t=1}^{T} g_t$$

and
$$\varepsilon_t = e_t - T^{-1} \sum_{t=1}^T e_t$$
 for $t = 1, \dots, T$.

- Note that $\varepsilon_t \approx e_t \mathbb{E}e_t = e_t$ for large T, since we assume that (e_t) is stationary and has mean zero.
- ▶ However, in general, (x_t) and (y_t) do not behave the same as $(f_t \mathbb{E}f_t)$ and $(g_t \mathbb{E}g_t)$ even asymptotically, since (f_t) and (g_t) are nonstationary.
- ▶ We mainly deal with the demeaned densities (x_t) and (y_t) in our statistical analysis.

Demeaned Densities and Moment Functions

- We assume that the densities (f_t) and (g_t) all have supports included in a compact subset K of \mathbb{R} , for $t = 1, \ldots, T$.
- ▶ Then the demeaned densities (x_t) and (y_t) take values in

$$L_0^2(K) = \left\{ w \in H \left| \int_K w(s) ds = 0, \int_K w^2(s) ds < \infty \right. \right\},$$

which is a subspace of the Hilbert space $L^2(\mathbb{R})$ of square integrable functions on \mathbb{R} endowed with the usual inner product.

▶ The moment functions ι_{κ} are redefined as

$$\iota_{\kappa}(s) = s^{\kappa} - \frac{1}{|K|} \int_{V} s^{\kappa} ds,$$

where |K| denotes the length of K, so that they belong to $L^2_0(K)$.

For all our actual computations, we use an approximate one-to-one correspondence between $L_0^2(K)$ and \mathbb{R}^M for some large M using a Wavelet basis in $L_0^2(K)$.

Stationarity and Nonstationarity Subspaces

- ▶ We allow for nonstationarity in (f_t) and (g_t) . More precisely, the coordinate processes $(\langle v, f_t \rangle)$ and $(\langle w, g_t \rangle)$ are allowed to have unit roots in the directions of some v and w for $v, w \in H$.
- ▶ Stationarity subspaces F_S and G_S of (f_t) and (g_t) are defined as the subspaces of H defined as

$$F_S = \{v \in H | \langle v, f_t \rangle \text{ is stationary} \}$$
$$G_S = \{w \in H | \langle w, g_t \rangle \text{ is stationary} \},$$

- Nonstationarity subspaces F_N and G_N of (f_t) and (g_t) are defined as orthogonal complements of F_S and G_S , so that $H = F_N \oplus F_S = G_N \oplus G_S$.
- ▶ We only consider the unit root type nonstationarity in (f_t) and (g_t) , and therefore the time series $(\langle v, f_t \rangle)$ and $(\langle w, g_t \rangle)$ are unit root processes for all $v \in F_N$ and $w \in G_N$.

Distributional Cointegration

- ▶ If (f_t) and (g_t) have the unit root type nonstationarity, it is natural to consider the possibility that some of their coordinate processes are cointegrated.
- ▶ That is, for some $v \in F_N$ and $w \in G_N$, we may have

$$\langle w, g_t \rangle = \pi + \langle v, f_t \rangle + u_t$$

with some constant π , where (u_t) is a general stationary process with mean zero.

Distributional Cointegrating Function

- Assume F_N and G_N are p- and q-dimensional and there are p- and q-unit roots in (f_t) and (g_t) , respectively.
- ▶ Therefore, we have v_1, \ldots, v_p and w_1, \ldots, w_q , which are linearly independent and span F_N and G_N , such that $\langle v_i, f_t \rangle$ and $\langle w_j, g_t \rangle$ are unit root processes for $i=1,\ldots,p$ and $j=1,\ldots,q$. If the (p+q)-dimensional unit root process (z_t) defined as

$$z_t = (\langle v_1, f_t \rangle, \dots, \langle v_p, f_t \rangle, \langle w_1, g_t \rangle, \dots, \langle w_q, g_t \rangle)'$$

is cointegrated with the cointegrating vector

$$c = (-a_1, \ldots, -a_p, b_1, \ldots, b_q)',$$

then the distributional cointegration holds with

$$v = a_1v_1 + \dots + a_pv_p$$
 and $w = b_1w_1 + \dots + b_qw_q$.

▶ The pair of functions v and w are called distributional cointegrating functions of two time series (f_t) and (g_t) of densities.

Longrun Response Function

Denote the distributional cointegrating functions by

$$v^{C} = a_1 v_1 + \dots + a_p v_p$$
$$w^{C} = b_1 w_1 + \dots + b_q w_q$$

- ▶ The distributional cointegrating function (v^C, w^C) of (f_t) and (g_t) measures the longrun response v^C of the time series of cross-sectional distribution represented by (f_t) on the time series $(\langle w^C, g_t \rangle)$.
- ▶ In particular, we define v^C to be the longrun response function of (f_t) on $(\langle w^C, g_t \rangle)$, which we may interpret as summarizing the longrun effect of (f_t) on the longrun movement of (g_t) in the direction of w^C .

Possible Number of Cointegrating Relations

- ▶ Clearly, there are at most r-number of linearly independent distributional cointegrating relationships, $r \leq \min(p, q)$, between (f_t) and (g_t) .
- Otherwise we would have a cointegrating vector c of the form $c=(-a_1,\ldots,-a_p,0,\ldots,0)'$ or $c=(0,\ldots,0,b_1,\ldots,b_q)'$, which implies that there is a linear combination of v_1,\ldots,v_p or w_1,\ldots,w_q whose inner product with (f_t) or (g_t) becomes stationary.
- ▶ This contradicts the assumption that v_1, \ldots, v_p and w_1, \ldots, w_q are linearly independent functions that span F_N and G_N , respectively.

Distributional Cointegration

▶ The distributional cointegration does not presume any distributional regression relationship like $g_t = \mu + Af_t + e_t$. However, for two time series of densities (f_t) and (g_t) that are given by the above distributional regression model, we may easily deduce that

Lemma Let (f_t) and (g_t) be given by the distributional regression model $g_t = \mu + Af_t + e_t$ with some stationary (e_t) . Then for any $w \in G_N$, we have $A^*w \notin F_S$ and the distributional cointegration

$$\langle w, g_t \rangle = \pi + \langle v, f_t \rangle + u_t$$

holds with $v = P_N A^* w$.

Longrun Response to Cross-sectional Moments

If (f_t) and (g_t) are given by the distributional regression $g_t = \mu + Af_t + e_t$, then we have

$$G_C = G_N$$
 and $r = q \le p$,

In this case, there exists a distributional cointegrating function (v^C,w^C) with

$$w^C = Q_N \iota_{\kappa}$$

Then it follows that

$$\langle w^C, g_t \rangle = \langle Q_N \iota_{\kappa}, g_t \rangle = \langle \iota_{\kappa}, Q_N g_t \rangle = \langle \iota_{\kappa}, g_t^N \rangle,$$

where $g_t^N = Q_N g_t$ is the nonstationary component of (g_t) .

► Therefore, we may interpret the corresponding v^C as the longrun response function of (f_t) to the κ -th cross-sectional moment of (g_t^N) , or the κ -th longrun cross-sectional moment of (g_t) .

Test for Distributional Cointegration

- Assume that we find p and q, the numbers of unit roots in (f_t) and (g_t) , and obtain consistent estimates (v_i^T) of (v_i) and (w_j^T) of (w_j) , $i=1,\ldots,p$ and $j=1,\ldots,q$, which span the nonstationary subspaces F_N and G_N of (f_t) and (g_t) .
- \blacktriangleright To test for distributional cointegration, we let (z_t^T) be defined as

$$z_t^T = \left(\langle v_1^T, x_t \rangle, \dots, \langle v_p^T, x_t \rangle, \langle w_1^T, y_t \rangle, \dots, \langle w_q^T, y_t \rangle \right)'$$

- ▶ Clearly, the test τ_n^T to determine the number of distributional unit roots may be used to test for the number of unit roots in (z_t) , $z_t = \left(\langle v_1, x_t \rangle, \ldots, \langle v_p, x_t \rangle, \langle w_1, y_t \rangle, \ldots, \langle w_q, y_t \rangle\right)'$.
- ▶ The maximum number of unit roots for (z_t) is of course given by p + q (no distributional cointegration in (f_t) and (g_t)).
- ▶ *n*-number of unit roots for (z_t) implies r-number of cointegrating relationships with r = (p + q) n.

Empirical Illustrations

Income-Consumption Dynamics

Interactive Income-Consumption Dynamics

- As an application of our model and methodology, we analyze the interactions between the income and consumption dynamics.
- For our analysis, we apply our theory developed thus far with (f_t) and (g_t) representing the time series of household income and household consumption distributions.

Data

- The cross-sectional observations of household income and consumptions are obtained at monthly frequency from Consumer Expenditure Survey (CES), collected for Bureau of Labor Statistics, US Census Bureau.
- CES consists of two surveys Quarterly Interview Survey and Diary Survey, that provide information on buying habits, expenditures, income, and consumer unit (families and single consumers) characteristics. CES is the only Federal survey to provide information on complete range of consumer expenditures and incomes.
- ➤ The data set provides 400 time series observations from October 1979 to February 2013, with cross-sectional observations for each month ranging from 1,537 to 5,406.
- During this sample period, each household is included in the survey at most five times, and therefore CES provides a pseudo panel data.

More on Data

- In order to construct monthly household income and consumption, we follow the definitions in Krueger and Perri (2006), and aggregate the monthly values provided in Universal Classification Code (UCC) level for each month and year.
- We then deflated the nominal income and consumption values by monthly CPI provided by BLS for all urban households with using a base year which varies among 1982, 1983 and 1984.
- ► The survey uses topcodes which may change annually and be applied at a different starting point. We drop all top-coded values.
- As in Krueger and Perri (2006), we correct expenditure on food, impute services from vehicle and primary residence, and exclude observations with possible measurement error or inconsistency problem.

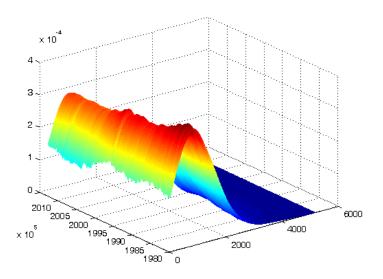
Interactive Dynamics of Income and Consumption

lf

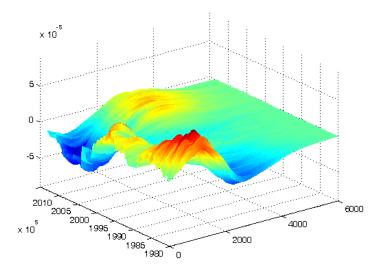
- ▶ the time series of income distributions has *p* unit roots
- \triangleright the time series of consumption distributions has q unit roots
- \triangleright there are r cointegrating relationships between them

Then, there are (p+q)-r unit roots in their time series combined together.

Densities of Household Incomes



Demeaned Densities of Household Incomes



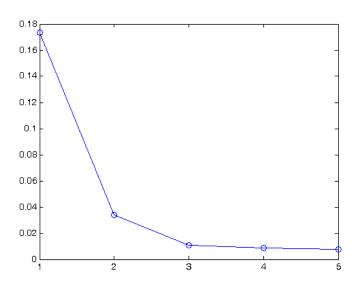
Unit Root Dimension - Incomes

To determine the unit root dimension n in the time series of cross-sectional distributions of household incomes, use the test $\hat{\tau}_n^T$ to test $\mathsf{H}_0: \dim(H_N) = n$ against $\mathsf{H}_1: \dim(H_N) \leq n-1$ with $n=1,\ldots,5$.

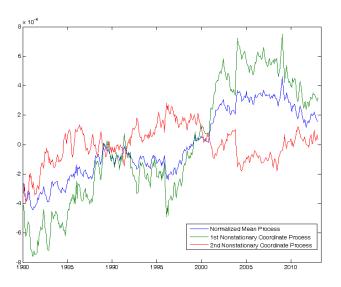
| \overline{M} | 1 | 2 | 3 | 4 | 5 |
|------------------|--------|--------|--------|--------|--------|
| $\hat{\tau}_n^T$ | 0.1734 | 0.0338 | 0.0106 | 0.0088 | 0.0076 |

- ▶ Our test, strongly and unambiguously, rejects H_0 against H_1 successively for n=5,4,3. Clearly, however, the test cannot reject H_0 in favor of H_1 for n=2.
- ▶ We conclude that there exists two-dimensional unit root, and set $\hat{n}_T = 2$.

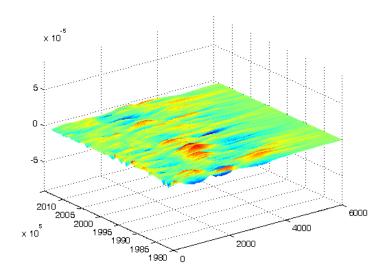
Scree Plot of Eigenvalues - Incomes

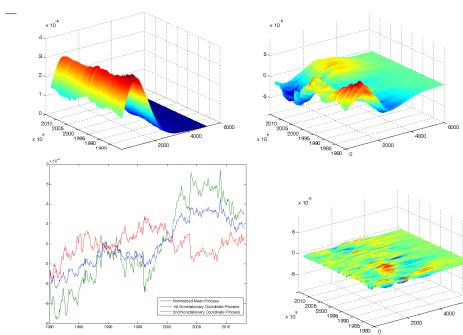


Integrated Coordinate Processes - Incomes



Stationary Components - Incomes





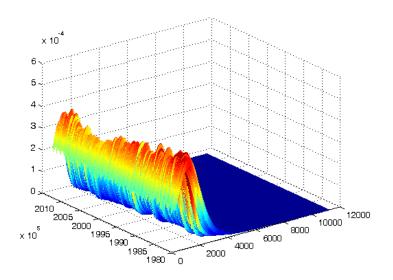
UR Proportions in Moments - Incomes

Compute the unit root portion estimates $\hat{\pi}_{\kappa}^{T}$ for the cross-sectional distributions of household incomes with $\hat{n}_{T}=2$ for the first four moments.

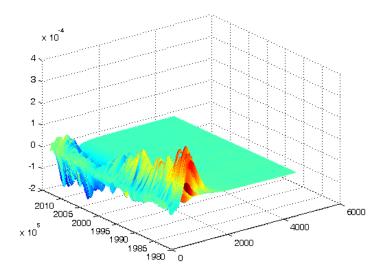
| $\hat{\pi}_1^T$ | $\hat{\pi}_2^T$ | $\hat{\pi}_3^T$ | $\hat{\pi}_4^T$ |
|-----------------|-----------------|-----------------|-----------------|
| 0.5734 | 0.3943 | 0.2755 | 0.2011 |

- ➤ The unit root proportions for the first four moments of the cross-sectional household income distributions are all substantially large. In particular, the unit root proportions for the first two moments are quite substantial.
- Nonstationarity in the cross-sectional household income distributions would certainly make their volatilities more persistent.

Densities of Household Consumptions



Demeaned Densities of Household Consumptions



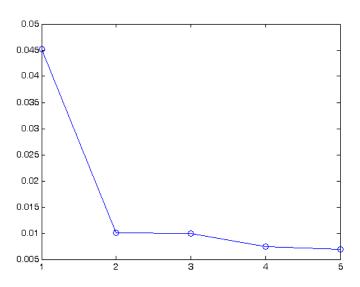
Unit Root Dimension - Consumptions

To test for existence of unit root in time series of cross-sectional distributions of household consumptions, use the statistic $\hat{\tau}_n^T$ to test $\mathsf{H}_0: \dim(H_N) = n$ against $\mathsf{H}_1: \dim(H_N) \leq n-1$ with $n=1,\ldots,5$.

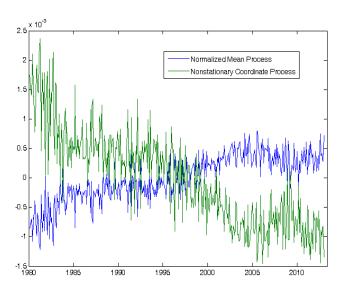
| \overline{M} | 1 | 2 | 3 | 4 | 5 |
|-----------------|--------|--------|--------|--------|--------|
| $\hat{	au}_n^T$ | 0.0452 | 0.0100 | 0.0099 | 0.0075 | 0.0069 |

- ▶ Our test successively rejects the null against the alternative for n = 5, 4, 3, 2.
- ▶ However, at 5% level, the test cannot reject H_0 in favor of H_1 for n = 1. Our test result implies $\hat{n}_T = 1$.

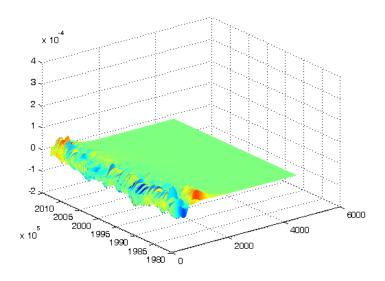
Scree Plot of Eigenvalues - Consumptions

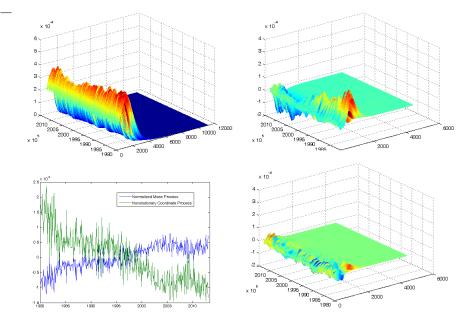


Integrated Coordinate Processes - Consumptions



Stationary Components - Consumptions





UR Proportions in Moments - Consumptions

Compute the estimates $\hat{\pi}_{\kappa}^T$ of the unit root proportions π_{κ} for the first four moments of the cross-sectional distributions of household consumption, with $\hat{n}_T=1$.

| $\hat{\pi}_1^T$ | $\hat{\pi}_2^T$ | $\hat{\pi}_3^T$ | $\hat{\pi}_4^T$ |
|-----------------|-----------------|-----------------|-----------------|
| 0.5598 | 0.4483 | 0.3595 | 0.3169 |

► The unit root proportions are also substantial for all of the first four moments.

Distributional Cointegration

- ▶ $H_N(f)$ and $H_N(g)$ are estimated to be 2- and 1-dimensional and there are 2- and 1-unit roots in (f_t) and (g_t) , denoting income and consumption distributions.
- ▶ Therefore, v_1, v_2 and w_1 span $H_N(f)$ and $H_N(g)$, such that $\langle v_1, f_t \rangle$, $\langle v_2, f_t \rangle$ and $\langle w_1, g_t \rangle$ are unit root processes.
- ▶ If 3-dimensional process (z_t)

$$z_t = (\langle v_1, f_t \rangle, \langle v_2, f_t \rangle, \langle w_1, g_t \rangle)'$$

is cointegrated with the cointegrating vector

$$c = (\alpha_1, \alpha_2, \beta_1)',$$

then the distributional cointegration holds with the cointegrating functions of (f_t) and (g_t) given by

$$v^C = \alpha_1 v_1 + \alpha_2 v_2 \quad \text{and} \quad w^C = \beta_1 w_1.$$

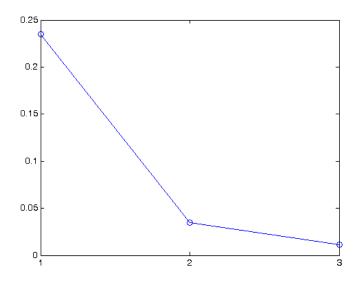
Test for Distributional Cointegration

- We may use τ_n^T also in this case to find the number of unit roots in (z_t) , containing all unit root process from the time series of income and consumption distributions by testing $H_0: (p+q)-r=n$ against $H_1: (p+q)-r \leq n-1$.
- ▶ Given p=2 and q=1, we may have up to three unit roots in the time series of income and consumption distributions together. Therefore, we consider only n=1,2 and 3.

| \overline{n} | 1 | 2 | 3 |
|-----------------|--------|--------|--------|
| $\hat{	au}_n^T$ | 0.2347 | 0.0350 | 0.0113 |

- ▶ Our test rejects H_0 against H_1 for n=3. However, the test cannot reject H_0 in favor of H_1 for n=2, giving (p+q)-r=2.
- ▶ This implies r = 1, i.e., the presence of a single cointegrating relationship between income and consumption distributions.

Scree Plot - Distributional Cointegration Test



Cointegrating Function

- Let v_1 and v_2 be orthonormal functions that span the nonstationary subspace F_N of the time series (f_t) of income distributions, and let w be the normalized function generating the nonstationary subspace G_N of the time series (g_t) of consumption distribution.
- ▶ We find one cointegrating relation between income and consumption distributions, and therefore, there exists constants a_1, a_2 and b such that

$$b\langle w, g_t \rangle = \delta + a_1 \langle v_1, f_t \rangle + a_2 \langle v_2, f_t \rangle + u_t$$

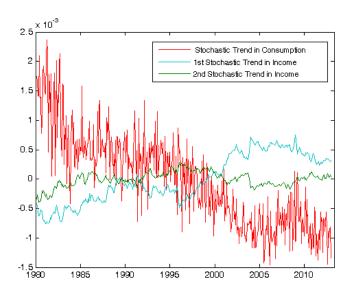
with some constant function δ and general stationary process (u_t) with mean zero.

▶ In this case, we have

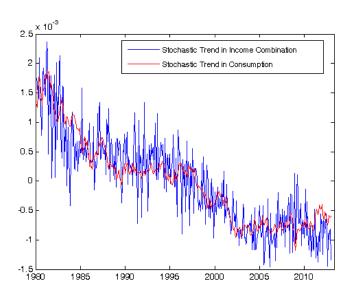
$$v_C = a_1v_1 + a_2v_2$$
 and $w_C = bw$,

where (v_C, w_C) is the cointegrating function of (f_t) and (g_t) .

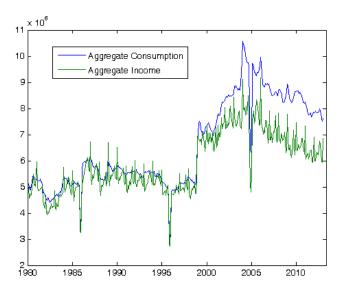
Stochastic Trends in Income and Consumption



Common Trends in Income and Consumption



Aggregate Income and Aggregate Consumptions



Longrun Response of Income to Consumption

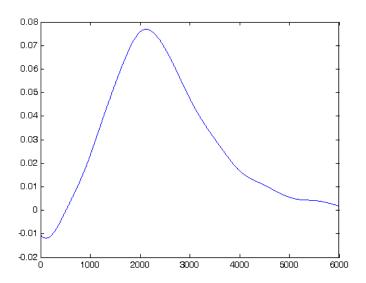
ightharpoonup We may readily obtain estimates of v_C and w_C , which we define as

$$v_C^T = a_1^T v_1^T + a_2^T v_2^T \quad \text{and} \quad w_C = b^T w^T,$$

from our estimates v_1^T, v_2^T and w^T of v_1, v_2 and w, and a_1^T, a_2^T and b^T of a_1, a_2 and b.

- ▶ The estimates v_1^T, v_2^T and w^T are obtained from our testing procedure for distributional unit roots, and the estimates a_1^T, a_2^T and b^T from our testing procedure for distributional cointegration, respectively in and between household income and consumption distributions.
- ▶ The estimated longrun response function of income distribution to consumption distribution is given by v_C^T .

Longrun Response Function



Empirical Findings

- ► The longrun trend in consumption is most affected by the income group with monthly earnings slightly over \$2,000. Roughly, all households with monthly earnings between \$1,000 and \$4,000 seem to play important roles in determining the persistent stochastic trend in consumption. As the level of monthly earning decreases below \$1,000, the longrun component of household's income has very little impact on the longrun consumption.
- ▶ The longrun component of household's income for the rich also does not have any major effect on the longrun consumption, though the magnitude of their effect decreases at a slower rate as their income increases than the rate it decreases as the income decreases for the poor.

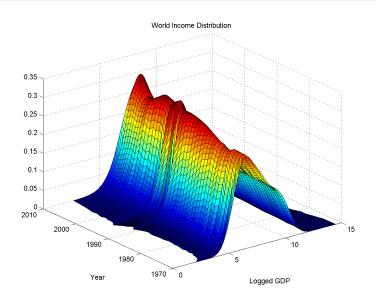
Note

- ▶ The income response to consumption is estimated to be negative for the household with monthly earnings less than approximately \$500, which we believe to be just an evidence of insignificant response.
- Observations for households with monthly earnings below approximately \$500 are scarce and irregular, so we do not expect to have any reliable results over very low income levels.

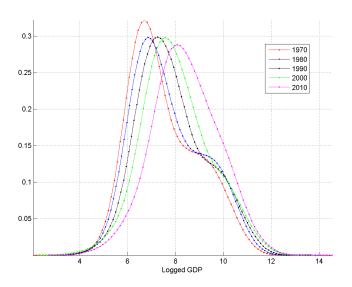
IV. Future Work

World Income Distributions

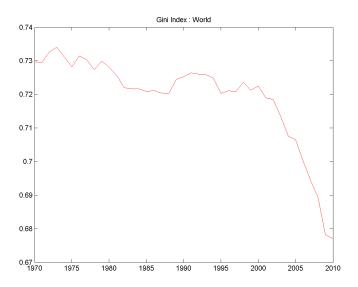
World Income Distributions - 3D



World Income Distributions - 2D

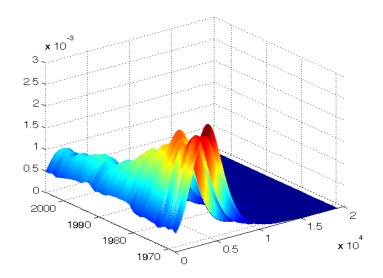


World Gini Coefficients

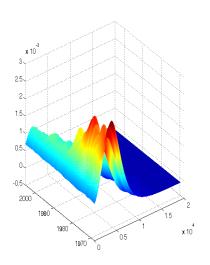


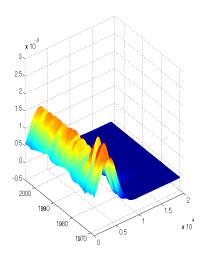
UK Income Distributions

UK Income Distributions

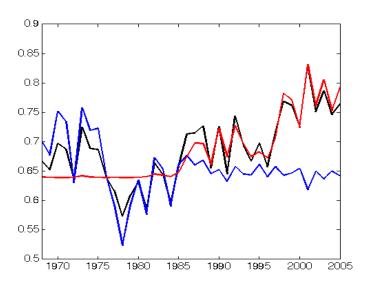


UK Incomes Decomposed

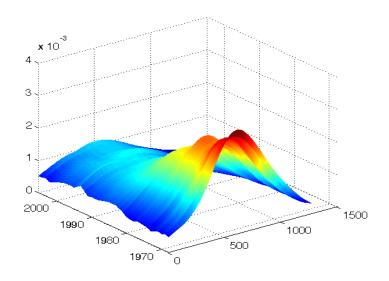




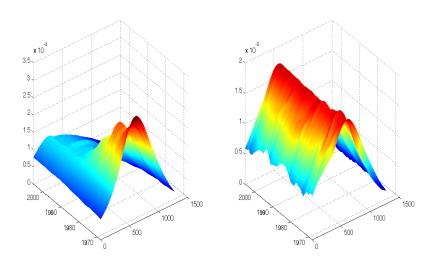
UK Gini Coefficients



UK Truncated Income Distributions



UK Truncated Incomes Decomposed



UK Truncated Gini Coefficients

